

### NEMA 17 integrated 1.8° 2-phase stepper motor with external shaft

#### Product overview

Lexium MDrive® Linear Actuator products integrate a 1.8° 2-phase stepper motor, external shaft linear mechanicals and drive electronics to deliver long life, high accuracy and repeatability in compact, low cost packages. A graphical user interface is provided for quick and easy parameter setup.

LMD linears may include a fully programmable motion controller with on-board I/O, enabling standalone motion control without need of an external controller. Real time closed loop performance is available for enhanced performance and feedback.

hMT closed loop performance is available in products with either a multi-turn absolute encoder or incremental magnetic encoder. Closed loop performance maintains functional motor control to prevent loss of synchronization, offers variable current control, torque control, and use of the motor's full torque range without derating.

Multi-turn absolute encoders may benefit users by detecting and storing position information, even when powered down. This can eliminate homing routines and reduce setup time at system startup.

#### Application areas

Lexium MDrive® Linear Actuator products are ideal for machine builders who want a robust motor with integrated electronics and linear mechanicals. Reduced system cabling can minimize problems due to electrical noise, while closed loop products deliver enhanced performance. Fewer individual system components also eliminate multiple potential failure points.



#### **Specifications**

Input power	Voltage		+12+48 VDC		
	Current maximum (1)		2.0 A		
Motor	Frame size	NEMA	17		
		inches	1.7		
		mm	42.7		
	Length	stack size	single		
Maximum thrust (2)	General purpose nut	lbs	25		
		kg	11		
	Anti-backlash nut	lbs	5		
		kg	2		
Maximum repeatability	General purpose nut	inch	0.005		
		mm	0.127		
	Anti-backlash nut	inch	0.0005		
		mm	0.0127		
Weight (without screw)		oz/g	13.6 / 385		
Step angle α		0	1.8		
Thermal	Operating temp	Heat sink maximum	85°C		
	non-condensing	Motor maximum	100°C		
Protection	Туре	Temperature warning	084°C, user selectable		
		Earth grounding	via product chassis ground lug		
		IP rating	IP20		
Communication versions	Pulse/Direction		RS-422/485 serial interface, 4 operating modes		
	Programmable Motion Control		RS-422/485 programmable with stored memory		
	CANopen		CANopen with programmable controller		
	Ethernet		EtherNetIP, Profinet, ModbusTCP		

<sup>(1)</sup> Actual power supply current will depend on voltage and load.

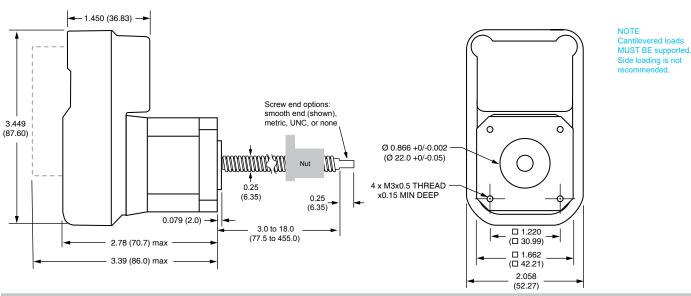


<sup>(2)</sup> Performance data for maximum force/load is based on a static load and will vary with a dynamic load.

### NEMA 17 integrated 1.8° 2-phase stepper motor with external shaft

#### LMD•42 Linear – external shaft, NEMA size 17

Dimensions in inches (mm), unless specified



Ø BCD

#### Nut specifications



General purpose nut

For applications not requiring antibacklash and wear compensation

Flange shape: round



Anti-backlash nut
Purpose: backlash free operation for
high accuracy and low drag torque.

purpose nut outline

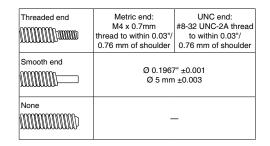
Flange shape: triangle

inches (mm)	Α	В	D	E	F	BCD	drag torque
General purpose	0.50 (12.7)	0.75 (19.1)	1.0 (25.4)	0.14 (3.6)	0.15 (3.81)	0.75 (19.1)	free wheeling
Anti- backlash	0.50 (12.7)	0.9 (22.86) max	1.0 (25.4)	0.143 (3.63)	0.18 (4.57)	0.75 (19.1)	< 1.0 oz-in < 0.7 N-cm

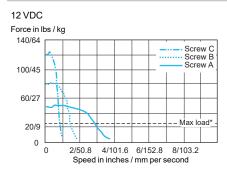
#### Lead screw specifications

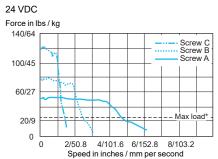
			Screw A	Screw B	Screw C
		0.25" / 6.35 mm	0.125" / 3.175 mm	0.063" / 1.588 mm	
	Per full step		0.00125" / 0.0317 mm	0.00063" / 0.0158 mm	0.00031" / 0.0079 mm
Load limit*	External shaft nuts	General purpose	25 lbs / 11 kg		
		Anti-backlash	5 lbs / 2 kg		
*Performance data for maximum force/load is based on a static load and will vary with a dynamic					

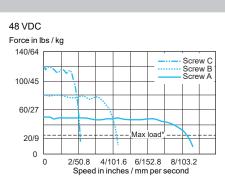
<sup>\*</sup>Performance data for maximum force/load is based on a *static* load and will vary with a *dynamic* load



#### Speed-force curves







<sup>\*</sup>Load limit is determined by selected nut. Performance data for maximun force/load is based on a static load and will vary with a dynamic load.

### NEMA 17 integrated 1.8° 2-phase stepper motor with external shaft





ICP0531

#### Accessories

for pluggable connector products			con	nm ty	pes	(1)
description	length feet (m)	part number	Р	М	Α	Е
Communication converters USB-pluggable converter to set/program communication parameters in 32- or 64-bit						
Mates to DB9 connector	6.0 (1.8)	MD-CC404-000	•	•		
Mates to DB9 connector. Includes: CAN dongle, terminating resistor, and pre-wired mating cables	6.0 (1.8)	MD-CC501-000			•	
Replacement mating connector kits						
Includes one 2-pin power mate, and one set (2 pieces) 7-pin multifunction mates	_	CK-14	•			
Includes one 2-pin power mate, and one set (2 pieces) 7-pin multifunction mates	_	CK-15		•	•	•

comm types (1)

P M A E

Communication converters USB-pluggable converter to set/program communication parameters in 32- or 64-bit						
Mates to M12 5-pin female connector	6.0 (1.8)	MD-CC405-000	•	•		
Mates to M12 5-pin male connector. Includes: CAN dongle, terminating resistor, and pre-wired mating cables	6.0 (1.8)	MD-CC502-000			•	
Cordsets Shielded cables pre-wired with straight M12 mating connectors						
Communication cordset mates to 5-pin female connector	10.0 (3.0)	MD-CS600-000	•	•		
Power cordset mates to 4-pin male connector	10.0 (3.0)	MD-CS620-000	•	•	•	•
I/O cordset mates to 12-pin female connector	10.0 (3.0)	MD-CS630-000	•			
I/O cordset mates to 12-pin male connector	10.0 (3.0)	MD-CS610-000		•	•	•
Communication cordset mates to 4-pin female connector	6.5 (2.0)	MD-CS640-000				•

length feet (m) part number

MD-CS650-000

10.0 (3.0)

description

Daisy chaining
Connect multiple units together in sequence with Y cable. Termination plug, sold separately, is required at end of run.

Communication cordset mates to 5-pin male connector

Y cable mates to M12 communication connector	0.3 (1.0)	MD-CS660-000		•	
M12 bus termination (resistor) plug	_	PLG-M12TP		•	

for M12 circular connector products

(1) Communication types:
P = Pulse/Direction via RS-422/485 serial interface
M = Programmable Motion Control via RS-422/485 serial interface
A = CANopen interface
E = EtherNet/IP, ModbusTCP, Profinet, MCode/TCP

for all products with Absolute Encoder		
description	length feet (m)	part number
Back-up battery pack Extend stored position data up to 5-years for 1 to 6 LMD units		
Battery pack, DIN-rail mount. Uses 3 AA batteries, not provided	_	ICP0531
LMD mating cable(s) with crimp connector to flying lead end	3.3 (1.0)	PD02-0531-FL1
PLC mating cable with crimp connector to flying lead end	3.3 (1.0)	PD04-0531-FL1

www.motion.schneider-electric.com

### NEMA 17 integrated 1.8° 2-phase stepper motor with external shaft



#### pluggable connectors

LEDs two signal indicators

#### Connectors

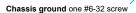
P1: Power 2-pin screw lock

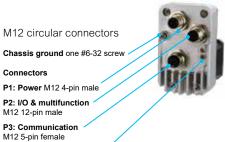
P2: I/O & multifunction 2 keyed 7-pin spring lock

LEDs two signal indicators

P3: Communication

DB9 male





#### Part numbers

Example	LMDCM421P-LA3M060G
Product LMD = Lexium MDrive, with linear actuator external shaft	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
Control type C = Closed loop / with hMT and encoder (1) A = Closed loop / with hMT and multi-turn absolute encoder O = Open loop / no hMT or encoder	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
Communication type P = Pulse/Direction via RS-422/485 serial interface (2) M = Programmable Motion Control via RS-422/485 serial interface A = CANopen interface E = EtherNet/IP, ModbusTCP, Profinet, MCode/TCP	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
<b>Flange size</b> <b>42</b> = NEMA 17 / 42mm	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
Motor length 1 = single stack	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
Connector style P = pluggable connectors, IP20 rating C = M12 circular connectors, IP20 rating	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
Lead screw -LA=0.25"/6.35 mm -LB=0.125"/3.175 mm -LC=0.063"/1.588 mm	L M D C M 4 2 1 P -LA 3 M 0 6 0 G <sup>-</sup>
Shaft style 3 = external shaft	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
Screw end finish  M = metric U = UNC S = smooth Z = none	L M D C M 4 2 1 P -LA 3 M 0 6 0 G 3
Screw length (3)	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
lengths available in 0.1" increments 030 = 03.0" / 76 mm minimum 180 = 18.0" / 457 mm maximum	
Nut G = general purpose A = anti-backlash	L M D C M 4 2 1 P -LA 3 M 0 6 0 G
Screw coating T = Teflon® Z = none	L M D C M 4 2 1 P -LA 3 M 0 6 0 G

- (1) Closed loop control delivers encoder feedback and hMT enhanced motor performance.
- (2) Open or closed loop only, not available with absolute encoder.
- (3) To calculate screw length: screw length = [desired stroke length] + [nut length] + [mounting surface plate thickness]

370 North Main Street
Marlborough, CT 06447
Phone: (860) 295-6102
Fax: (860) 295-6107

Intelligent motion systems

