

LMD•P85 Pulse/direction input

Product overview

Robust Lexium MDrive® Pulse/Direction products integrate 1.8° 2-phase stepper motors with onboard control electronics and hMT closed loop performance. Products have 4 modes of operation: pulse/direction input, variable speed control, constant velocity drive, and variable torque control.

With an RS-422/485 serial interface, settings can be downloaded and stored in nonvolatile memory. Commissioning, parameterization and monitoring is done via the user-friendly software provided.

Products may include an encoder, which is internal to the unit so no extra space is required. Encoders perform stall detection, position maintenance and find index mark, in addition to monitoring motor shaft position for real time closed loop feedback.

Application areas

Especially well suited for industrial applications, products include an IP65 rated version with circular M12 connectors. A high torque motor (LMH•P85) is also available, increasing torque up to 50%.

Lexium MDrive products can reduce machine complexity, size and cost in many stepper and servo motor applications. Their high degree of integration can increase system reliability by reducing the number of individual components, eliminating multiple potential failure points.



LMD•P85 Lexium MDrive Pulse/direction input products: integrated NEMA34 motor and controls, IP65 & IP20-rated

General features

Robust integrated microstepping drive and NEMA34 1.8° 2-phase stepper motor				
Advanced current control for exceptional performance and smoothness				
RS-422/485 serial interface with 4 operating modes: pulse/direction, speed, torque and velocity control				
+12 to +70 VDC single supply				
20 microstep resolutions up to	51,200 steps per rev including: Degrees, Metric, Arc Minutes			
Hardware I/O Sourcing or sinking				
	Analog input, signal inputs, power outputs, high-speed signal output			
Protection Temperature warning				
	IP20, IP65 ratings			
Encoder	1000 lines / 4000 edges per rev			
	internal magnetic			
0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments				
Graphical user interface provided for quick and easy parameter setup				
4 year conditional warranty				



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Specifications

Protocol type		RS-422/485
Voltage	VDC	+12+70
Current maximum (1)	Amp	4.0
Frame size	NEMA	34
	inches	3.4
	mm	85
Performance levels		standard torque or premium high torque (2)
Holding torque	oz-in	336920
	N-cm	237650
Length	stack sizes	1, 2 & 3
Operating temp	Heat sink maximum	85°C
non-condensing	Motor maximum	100°C
Туре	Temperature warning	084°C, user selectable
	IP rating	IP20, IP65
	Earth grounding	via product chassis ground lug
Microstep resolution	Number of settings	20
	Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 arc minute/µstep), 25400 (0.001mm/µstep)
Encoder	Line count	1000 lines / 4000 edges per rev
	Style	internal, magnetic
	Outputs	6 TTL level compatible
Operating modes	Open loop configuration	pulse/direction input, speed control, velocity mode
	Closed loop configuration (3)	pulse/direction input, speed control, velocity mode, variable torque mode
Digital filter range		50 nS12.9 μS (10 MHz38.8 kHz)
Clock types (step mode)		step/direction, quadrature, step up/step down, clockwise/counterclockwise
Step frequency	Maximum	2.56 MHz
	Voltage Current maximum (1) Frame size Performance levels Holding torque Length Operating temp non-condensing Type Microstep resolution Encoder Operating modes Digital filter range Clock types (step mode)	Voltage VDC Current maximum (1) Amp Frame size NEMA inches mm Performance levels Oz-in N-cm Holding torque oz-in N-cm Length stack sizes Operating temp non-condensing Heat sink maximum Type Temperature warning IP rating Earth grounding Earth grounding Number of settings Steps per revolution Steps per revolution Encoder Line count Style Outputs Operating modes Open loop configuration Closed loop configuration (3) Digital filter range Clock types (step mode)

⁽¹⁾ Actual power supply current will depend on voltage and load.

Setup parameters

Operating modes Basic		Pulse/direction	microstep resolution, run current, hold current, hold delay, clock mode, motion enable active, input filters				
	Advanced	Speed control	acceleration, decelaration, velocity, flags				
		Torque mode (4)	set torque speed, % maintained motor torque, torque current, filtering				
		Velocity control	acceleration, decelaration, velocity, slew, flags				
Device parameters	ers Analog input settings s		select range and resolution				
Communication bus settings I/O settings Motion settings hMT settings (3)		s settings	set baud rate, enable/disable party mode and features, check sum				
			clock and filter settings, attention output with selectable pre-programmed fields				
			select motion, analog and velocity settings as available by operating mode				
			hMT setup/status; hMT operation				
Device ID			device information, restore settings				

⁽⁴⁾ Only with closed loop products.

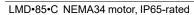
An optional Communication Converter is recommended to facilitate prototyping.

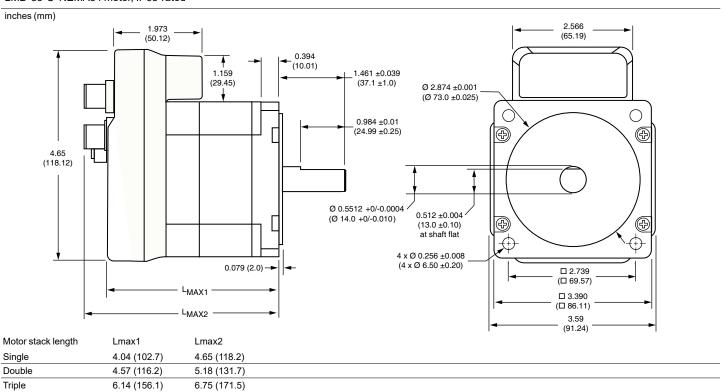
⁽²⁾ Contact the factory for product details.(3) Only with closed loop products.

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Dimensions

LMD•85 NEMA34 motor, IP20-rated inches (mm) 2.566 (65.19) (50.12) 0.394 (10.01) 1.159 1.461 ±0.039 (29.45)(37.1 ±1.0) Ø 2.874 ±0.001 (Ø 73.0 ±0.025) 0.984 ±0.01 (24.99 ±0.25) 4 **(** 4.65 (118.12) Ø 0.5512 +0/-0.0004 0.512 ±0.004 (Ø 14.0 +0/-0.010) **(** (13.0 ±0.10) at shaft flat 4 x Ø 0.256 ±0.008 (4 x Ø 6.50 ±0.20) 0.079 (2.0) -□ 2.739 (69.57) L_{MAX1} □ 3.390 (86.11) L_{MAX2} 3.59 (91.24) Motor stack length Lmax1 Lmax2 3.79 (96.2) 4.55 (115.7) Single 5.07 (128.8) Double 4.33 (110.0) 5.90 (149.9) 6.65 (168.9) Triple





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IP20-rated products

LEDs two signal indicators Chassis ground one #6-32 screw Connectors P1: Power 2-pin screw lock P2: I/O & multifunction 2 keyed 7-pin spring lock P3: Communication DB9 male

M12 12-pin female

IP65-rated products two signal indicators Chassis ground one #6-32 screw Connectors P1: Power M12 4-pin male P3: Communication M12 5-pin female P2: I/O & multifunction

MD-CC404-000 MD-CC405-000 MD-CS600-000 MD-CS620-000

Part numbers

example part number	L	М	D	С	Ρ	8	5	1	С
Product LMD = Lexium MDrive with standard hybrid stepper motor LMH = Lexium MDrive with high torque stepper motor (1)	L	M	D	С	Р	8	5	1	С
Control type C = Closed loop / with hMT and encoder (2) O = Open loop / no hMT or encoder	L	М	D	С	Р	8	5	1	С
Communication type P = Pulse/Direction via RS-422/485 serial interface	L	М	D	С	Р	8	5	1	С
Flange size 85 = NEMA 34 3.4" / 85mm	L	М	D	С	Р	8	5	1	С
Motor length 1 = single stack 2 = double stack 3 = triple stack	L	М	D	С	Р	8	5	1	С
Variation — omit from part number if unwanted C = M12 circular connectors and IP65 rating	L	М	D	С	Р	8	5	1	С

- (1) Contact the factory for product details.
- (2) Closed loop control delivers encoder feedback and hMT enhanced motor performance.

mate, and one set (2 pieces) 7-pin multifunction mates

Accessories

description

•	feet (m)	'
Communication converter USB-pluggable converter to set/program communication parameters in 32- or 64-bit		
Mates to DB9 connector	6.0 (1.8)	MD-CC404-000
Mates to M12 5-pin female connector	6.0 (1.8)	MD-CC405-000
IP65 cordsets Shielded cables pre-wired with straight M12 mating connectors.		
Communication cordset mates to 5-pin female connector	10.0 (3.0)	MD-CS600-000
Power cordset mates to 4-pin male connector	10.0 (3.0)	MD-CS620-000
I/O cordset mates to 12-pin female connector	10.0 (3.0)	MD-CS630-000
Replacement mating connector kit Kits are for IP20 products. They include one 2-pin power		

length

part number

CK-14

MD-CS630-000

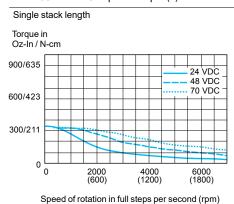
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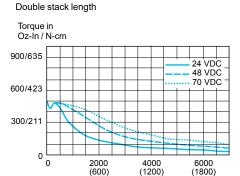
Motor performance

1 MD•85 N	FMA 34 motor	r specifications

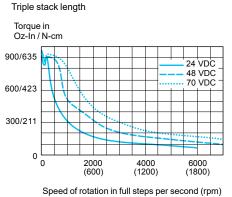
Motor	Stack length	Single	Single Double	
Holding torque	oz-in	336	480	920
Holding torque	N-cm	237	339	650
Detent torque	oz-in	10.9	10.9 14.16	
Detent torque	N-cm	7.7	10.0	14.0
Rotor inertia	oz-in-sec²	0.0127	0.0191	0.0382
Notor mertia	kg-cm ²	0.90	1.35	2.70
Radial load limit, center of shaft	lbs	65	65	65
Radial load lifflit, certier of shart	kg	29.4	29.4	29.4
Axial load limit @ 1500rpm	lbs	20	20	20
(5000 full steps/sec)	kg	9	9	9
Weight (motor+driver)	lb	4.45	5.65	9.0
weight (motor-unver)	kg	2.02	2.56	4.08

LMD•85 NEMA 34 speed torque (1)





Speed of rotation in full steps per second (rpm)



(1) Test conditions: 100% current with damper simulating load.

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Intelligent motion systems

