

Lexium MDrive®

LMD•M85 programmable Motion Control

Product overview

Robust Lexium MDrive® Motion Control products integrate 1.8° 2-phase stepper motors with control electronics. Included are on-board programmable motion controller for stand-alone operation, and optional hMT closed loop performance.

hMT closed loop performance is available in products with either a multi-turn absolute encoder or incremental magnetic encoder. Closed loop performance maintains functional motor control to prevent loss of synchronization, offers variable current control, torque control, and use of the motor's full torque range without derating.

Multi-turn absolute encoders may benefit users by detecting and storing position information, even when powered down. This can eliminate homing routines and reduce setup time at system startup.

Product parameterization, programming and monitoring is through user-friendly software with an RS-422/485 serial interface. Settings can be downloaded and stored in non-volatile memory.

Application areas

Especially well suited for industrial applications, products include an IP65 rated version with circular M12 connectors.

Compact Lexium MDrive products can reduce machine complexity, size and cost in many stepper and servo motor applications. Their high degree of integration can increase system reliability by reducing the number of individual components, eliminating multiple potential failure points.



LMD•M85 Lexium MDrive Motion Control products: integrated NEMA34 motor and controls, IP65 & IP20-rated

Features overview

General	NEMA34 1.8° 2-phase stepper motor integrated with robust control electronics, including programmable motion controller Advanced current control for exceptional performance and smoothness
Input power	+12 to +70 VDC single supply
Communication	RS-422/485 serial interface 62 software addresses for multi-drop communications Graphical user interface provided for quick and easy parameter setup
Encoder options	Multi-turn absolute or incremental magnetic
Motion	20 microstep resolutions up to 51,200 steps per rev including: Degrees, Metric, Arc Minutes 336 user program labels / 11,120 bytes flash memory 0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments
I/O, sourcing or sinking	+5 to +24 VDC signal inputs 12-bit analog input (1) 100ma power outputs 5.5mA high-speed signal output
Protection	Temperature warning IP20, IP65 ratings
Warranty	4 year, conditional

(1) Not available on products with multi-turn absolute encoder.

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Specifications

Communication	Protocol type		RS-422/485	
Input power	Voltage	VDC	+12...+70	
	Current maximum (1)	Amp	4.0	
Motor	Frame size	NEMA	34	
		inches	3.4	
		mm	85	
	Performance levels		standard torque or premium high torque (2)	
	Holding torque	oz-in		336...920
N-cm			237...650	
Thermal	Operating temp non-condensing	Heat sink maximum	85°C	
		Motor maximum	100°C	
	Type	Temperature warning		0...84°C, user selectable
		IP rating		IP20, IP65
Earth grounding			via product chassis ground lug	
I/O sourcing or sinking	One analog input (3)	Resolution	12 bit	
		Voltage range	0...+5 VDC, 0...+10 VDC, 0...20 mA, 4...20 mA	
	Four signal inputs	Voltage range		+5...+24 VDC, TTL level compatible
		Protection		over temp, short circuit, transient, over voltage, inductive clamp
	Two power outputs (4)	Current rating		-100...+100 mA
		Voltage range		-24...+24 VDC
	One high-speed signal output	Current open collector/emitter		5.5 mA
		Voltage open collector		+60 VDC
		Voltage open emitter		+7 VDC
	Aux. logic input	Voltage range (5)		+12...+24 VDC
Encoder options	Multi-turn absolute	Position update / retention	30 days on internal power; 5 years with optional battery pack	
	Incremental magnetic	Line count	1000 lines / 4000 edges per rev	
Motion	Microstep resolution	Number of settings	20	
		Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/μstep), 21600 (1 arc minute/μstep), 25400 (0.001mm/μstep)	
	Counters	Type		position, encoder/32 bit
		Edge rate maximum		5 MHz
	Velocity	Range		+/- 2,560,000
		Resolution		0.5961 steps per second
	Accel/Decel	Range		1.1 x 10 ⁹ steps per second ²
		Resolution		90.9 steps per second ²
		Types		linear, triangle s-curve, sinusoidal s-curve
	Software	Program storage	Type/size	flash / 11,120
		User registers	Number/resolution	4 / 32-bit
		Floating point registers	Number/precision	8 / double
		Math functions	Arithmetic	
Logic				AND, OR, XOR, NOT
Trigonometric				ABS, COS, ACOS, LOG2, LOG10, PI, SIN, ASIN, SQRT, TAN, ATAN
Branch functions			Branch & call	
I/O functions		Inputs		Home, limit plus, limit minus, go, stop, pause, jog plus, jog minus, general purpose, capture
		Outputs		Moving, error, velocity change,, moving position, trip, attention. general purpose
Trip functions				Trip on input, trip on position, trip on time, trip capture, trip on relative position, trip on main power loss
Party-mode addresses				62
Encoder functions (6)				stall detection, position maintenance, find index, hMT

(1) Actual power supply current will depend on voltage and load.

(2) Contact factory for details.

(3) Not available on products with multi-turn absolute encoder.

(4) Products with multi-turn absolute encoder have one power output.

(5) When input voltage is removed, maintains power only to control and feedback circuits.

(6) Closed-loop models with encoder only.

An optional Communication Converter is recommended to facilitate prototyping.



See User Manual for complete details: motion.schneider-electric.com/manuals

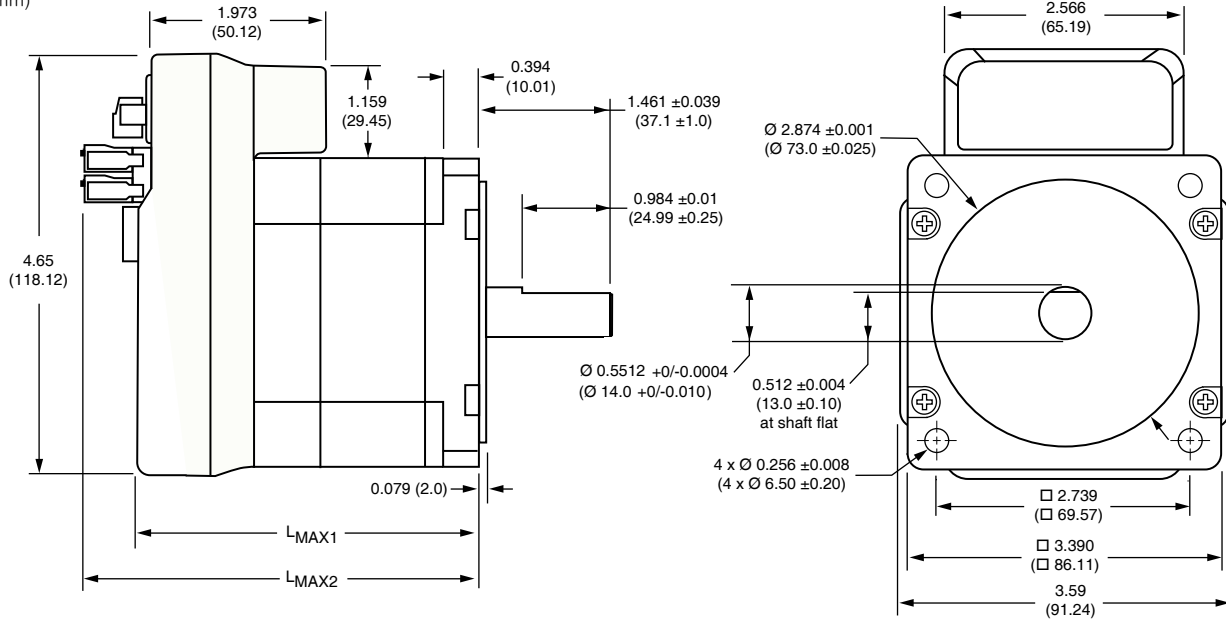
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Dimensions

LMD•85 NEMA34 motor, IP20-rated

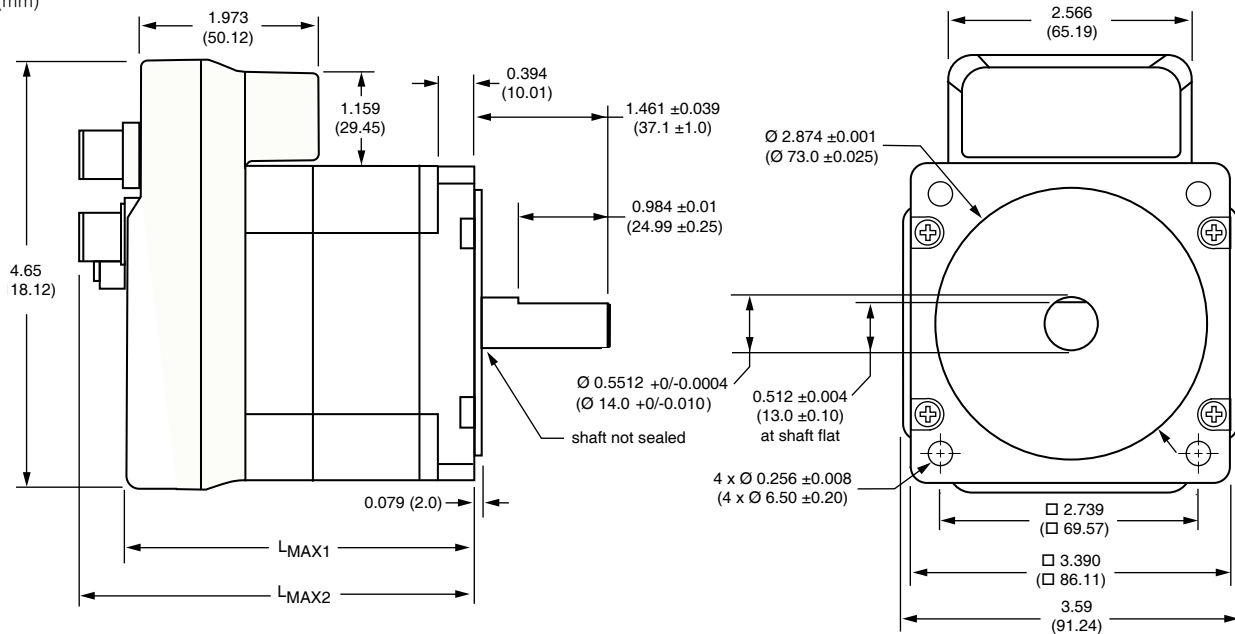
inches (mm)



Motor stack length	L_{max1}	L_{max2}
Single	3.79 (96.2)	4.55 (115.7)
Double	4.33 (110.0)	5.07 (128.8)
Triple	5.90 (149.9)	6.65 (168.9)

LMD•85•C NEMA34 motor, IP65-rated

inches (mm)

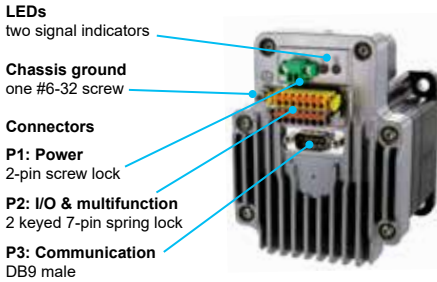


Motor stack length	L_{max1}	L_{max2}
Single	4.04 (102.7)	4.65 (118.2)
Double	4.57 (116.2)	5.18 (131.7)
Triple	6.14 (156.1)	6.75 (171.5)

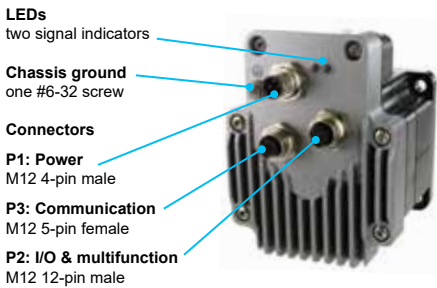
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IP20-rated products



IP65-rated products



Part numbers

example part number	L	M	D	C	M	8	5	1	C
Product	L	M	D	C	M	8	5	1	C
LMD = Lexium MDrive with standard hybrid stepper motor LMH = Lexium MDrive with high torque stepper motor (1)									
Control type	L	M	D	C	M	8	5	1	C
C = Closed loop / with hMT and incremental magnetic encoder (2) A = Closed loop / with hMT and multi-turn absolute encoder (2) O = Open loop / no hMT or encoder									
Communication type	L	M	D	C	M	8	5	1	C
M = programmable Motion Control via RS-422/485 serial interface									
Flange size	L	M	D	C	M	8	5	1	C
85 = NEMA 34 3.4" / 85mm									
Motor length	L	M	D	C	M	8	5	1	C
1 = single stack 2 = double stack 3 = triple stack									
Variation — omit from part number if unwanted C = M12 circular connectors and IP65 rating	L	M	D	C	M	8	5	1	C

(1) Contact the factory for product details.
(2) Closed loop control delivers encoder feedback and hMT enhanced motor performance.

Accessories

description	length feet (m)	part number
Communication converter		
USB-pluggable converter to set/program communication parameters in 32- or 64-bit		
Mates to DB9 connector	6.0 (1.8)	MD-CC404-000
Mates to M12 5-pin female connector	6.0 (1.8)	MD-CC405-000
IP65 cordsets		
Shielded cables pre-wired with straight M12 mating connectors		
Communication cordset mates to 5-pin female connector	10.0 (3.0)	MD-CS600-000
Power cordset mates to 4-pin male connector	10.0 (3.0)	MD-CS620-000
I/O cordset mates to 12-pin male connector	10.0 (3.0)	MD-CS610-000
Back-up battery pack for Absolute Encoder models		
Extend stored position data up to 5-years for 1 to 6 LMDs with absolute encoder		
Battery pack, DIN-rail mount. Uses 3 AA batteries, not provided	—	ICP0531
LMD mating cable(s) with crimp connector to flying lead end	3.3 (1.0)	PD02-0531-FL1
PLC mating cable with crimp connector to flying lead end	3.3 (1.0)	PD04-0531-FL1
Replacement mating connector kit		
Kits are for IP20 products. They include one 2-pin power mate, and one set (2 pieces) 7-pin multifunction mates	—	CK-15

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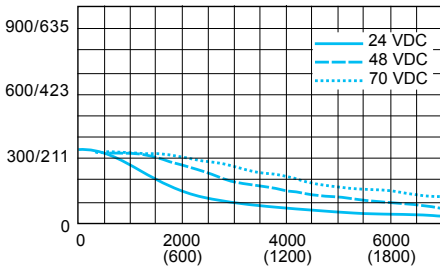
Motor performance

LMD•85 NEMA 34 motor specifications	Motor	Stack length	Single	Double	Triple
	Holding torque		oz-in	336	480
		N-cm	237	339	650
Detent torque		oz-in	10.9	14.16	19.83
		N-cm	7.7	10.0	14.0
Rotor inertia		oz-in-sec ²	0.0127	0.0191	0.0382
		kg-cm ²	0.90	1.35	2.70
Radial load limit, center of shaft		lbs	65	65	65
		kg	29.4	29.4	29.4
Axial load limit @ 1500rpm (5000 full steps/sec)		lbs	20	20	20
		kg	9	9	9
Weight (motor+driver)		lb	4.45	5.65	9.0
		kg	2.02	2.56	4.08

LMD•85 NEMA 34 speed torque (1)

Single stack length

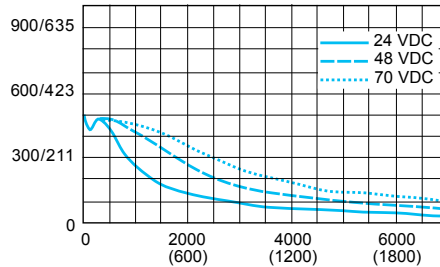
Torque in
Oz-In / N-cm



Speed of rotation in full steps per second (rpm)

Double stack length

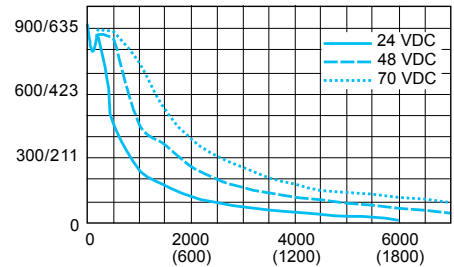
Torque in
Oz-In / N-cm



Speed of rotation in full steps per second (rpm)

Triple stack length

Torque in
Oz-In / N-cm



Speed of rotation in full steps per second (rpm)

(1) Test conditions: 100% current with damper simulating load.