

# Lexium MDrive®

## LMD•M85 programmable Motion Control

### Product overview

Robust Lexium MDrive® Motion Control products integrate 1.8° 2-phase stepper motors with control electronics, including an on-board programmable motion controller for stand-alone operation. An optional encoder, internal to the product, delivers hMT closed loop performance.

With an RS-422/485 serial interface, settings can be downloaded and stored in non-volatile memory. Parameterization, programming and monitoring is all done via the user-friendly software provided.

Products with encoder feature hMT closed loop performance to maintain functional motor control and prevent loss of synchronization. Benefits include: variable current control, torque control, using the motor's full torque range without derating.

### Application areas

Especially well suited for industrial applications, products include an IP65 rated version with circular

M12 connectors. A high torque motor (LMH•85) is also available, increasing torque up to 50%.

Lexium MDrive products can reduce machine complexity, size and cost in many stepper and servo motor applications. Their high degree of integration can increase system reliability by reducing the number of individual components, eliminating multiple potential failure points.



LMD•M85 Lexium MDrive Motion Control products: integrated NEMA34 motor and controls, IP65 & IP20-rated

### General features

Robust control electronics, including programmable motion controller, integrated with NEMA34 1.8° 2-phase stepper motor	
Advanced current control for exceptional performance and smoothness	
RS-422/485 serial interface	
+12 to +70 VDC single supply	
20 microstep resolutions up to 51,200 steps per rev including: Degrees, Metric, Arc Minutes	
62 software addresses for multi-drop communications	
Protection	0...84°C temperature warning, user selectable IP20, IP65 ratings
I/O, sourcing or sinking	+5 to +24 VDC signal inputs 12-bit analog input 100mA power outputs 5.5mA high-speed signal output
Encoder	1000 lines / 4000 edges per rev internal magnetic
336 user program labels / 11,120 bytes flash memory	
0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments	
Graphical user interface provided for quick and easy parameter setup	
4 year warranty	

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### Specifications

Communication	Protocol type		RS-422/485	
Input power	Voltage	VDC	+12...+70	
	Current maximum (1)	Amp	4.0	
Motor	Frame size	NEMA	34	
		inches	3.4	
		mm	85	
	Performance levels		standard torque or premium high torque (2)	
	Holding torque	oz-in		336...920
N-cm			237...650	
Thermal	Length	stack sizes	1, 2 & 3	
		Operating temp non-condensing		
	Heat sink maximum	85°C		
	Motor maximum	100°C		
Protection	Type	Temp warning	0...84°C, user selectable	
		IP rating	IP20, IP65	
		Earth grounding	via product chassis ground lug	
I/O sourcing or sinking	One analog input	Resolution	12 bit	
		Voltage range	0...+5 VDC, 0...+10 VDC, 0...20 mA, 4...20 mA	
	Four signal inputs	Voltage range	+5...+24 VDC, TTL level compatible	
		Protection	over temp, short circuit, transient, over voltage, inductive clamp	
	Two power outputs	Current rating	-100...+100 mA	
		Voltage range	-24...+24 VDC	
	One high-speed signal output	Current open collector/emitter	5.5 mA	
		Voltage open collector	+60 VDC	
		Voltage open emitter	+7 VDC	
	Aux. logic input	Voltage range (3)		+12...+24 VDC
Motion	Microstep resolution	Number of settings	20	
		Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/μstep), 21600 (1 arc minute/μstep), 25400 (0.001mm/μstep)	
	Encoder	Line count		1000 lines / 4000 edges per rev
		Style		internal, magnetic
	Counters	Type		position, encoder/32 bit
		Edge rate maximum		5 MHz
	Velocity	Range		+/- 2,560,000
		Resolution		0.5961 steps per second
	Accel/Decel	Range		1.5 x 10 <sup>9</sup> steps persecond <sup>2</sup>
		Resolution		90.9 steps per second <sup>2</sup>
		Types		linear, triangle s-curve, sinusoidal s-curve
	Software	Program storage	Type/size	flash / 11,120
		User registers	Number/resolution	4 / 32-bit
Floating point registers		Number/precision	8 / double	
Math functions		Arithmetic		+, -, x, ÷, >, <, =, >=, <=
		Logic		AND, OR, XOR, NOT
		Trigonometric		ABS, COS, ACOS, LOG2, LOG10, PI, SIN, ASIN, SQRT, TAN, ATAN
Branch functions			Branch & call	
I/O functions		Inputs		Home, limit plus, limit minus, go, stop, pause, jog plus, jog minus, general purpose, capture
		Outputs		Moving, error, velocity change,, moving position, trip, attention. general purpose
Trip functions				Trip on input, trip on position, trip on time, trip capture, trip on relative position, trip on main power loss
Party-mode addresses				62
Encoder functions (4)				stall detection, position maintenance, find index, hMT

(1) Actual power supply current will depend on voltage and load.

(2) Contact the factory for product details.

(3) When input voltage is removed, maintains power only to control and feedback circuits.

(4) Closed-loop models with encoder only

An optional Communication Converter is recommended to facilitate prototyping.



See User Manual for complete details: [motion.schneider-electric.com/manuals](http://motion.schneider-electric.com/manuals)

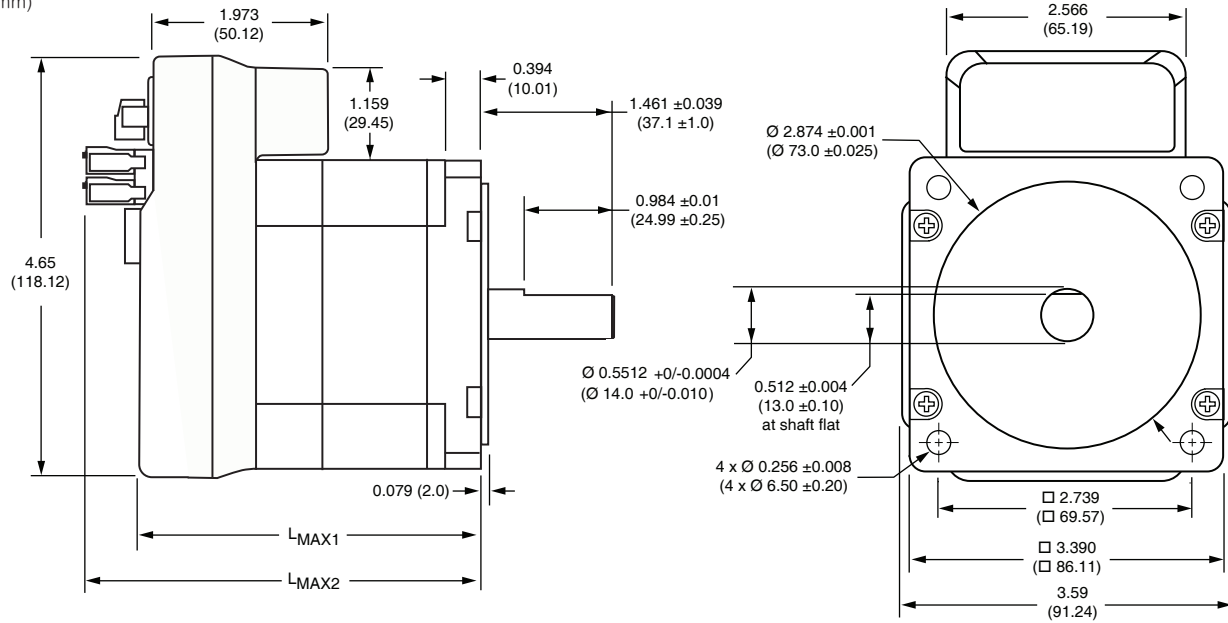
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## LMD•M85 programmable Motion Control

### Dimensions

#### LMD•85 NEMA34 motor, IP20-rated

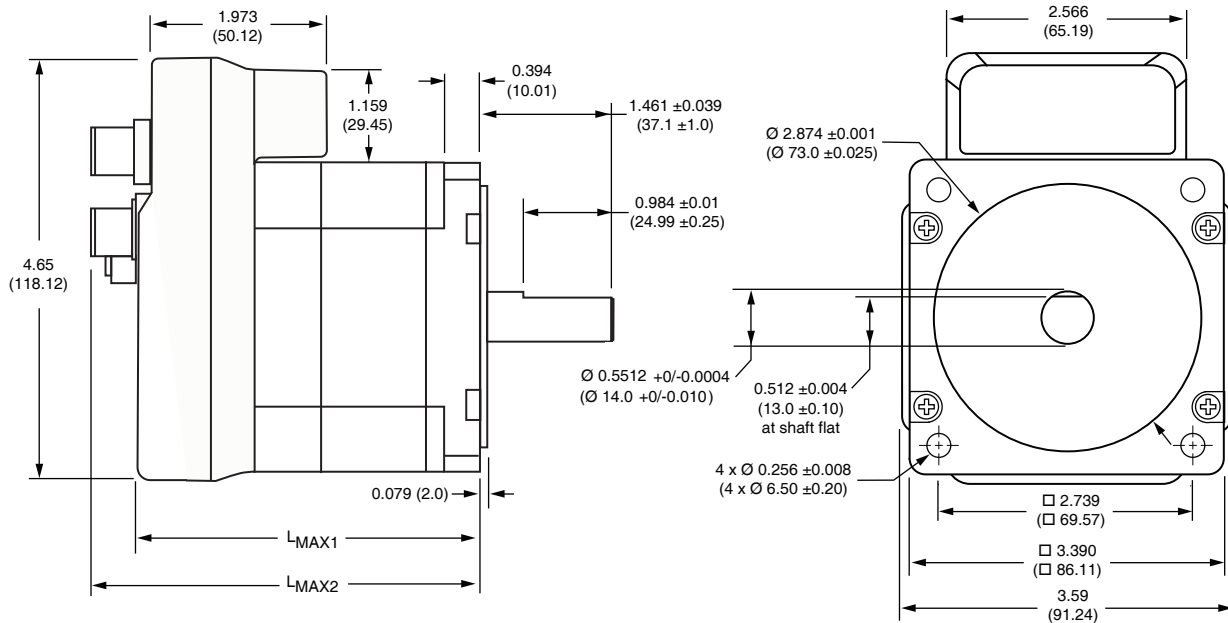
inches (mm)



Motor stack length	L <sub>max1</sub>	L <sub>max2</sub>
Single	3.79 (96.2)	4.55 (115.7)
Double	4.33 (110.0)	5.07 (128.8)
Triple	5.90 (149.9)	6.65 (168.9)

#### LMD•85•C NEMA34 motor, IP65-rated

inches (mm)

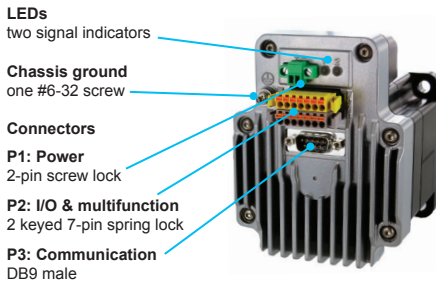


Motor stack length	L <sub>max1</sub>	L <sub>max2</sub>
Single	4.04 (102.7)	4.65 (118.2)
Double	4.57 (116.2)	5.18 (131.7)
Triple	6.14 (156.1)	6.75 (171.5)

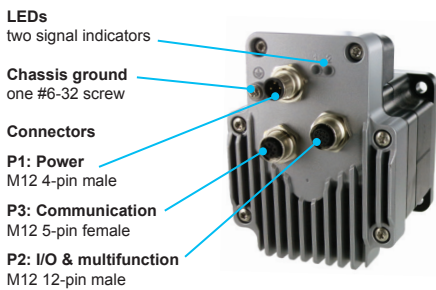
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## LMD•M85 programmable Motion Control

### IP20-rated products



### IP65-rated products



### Part numbers

example part number	L	M	D	C	M	8	5	1	C
<b>Product</b> LMD = Lexium MDrive with standard hybrid stepper motor LMH = Lexium MDrive with high torque stepper motor (1)	L	M	D	C	M	8	5	1	C
<b>Control type</b> C = Closed loop / with hMT and encoder (2) O = Open loop / no hMT or encoder	L	M	D	C	M	8	5	1	C
<b>Communication type</b> M = programmable Motion Control via RS-422/485 serial interface	L	M	D	C	M	8	5	1	C
<b>Flange size</b> 85 = NEMA 34 3.4" / 85mm	L	M	D	C	M	8	5	1	C
<b>Motor length</b> 1 = single stack 2 = double stack 3 = triple stack	L	M	D	C	M	8	5	1	C
<b>Variation</b> — omit from part number if unwanted C = M12 circular connectors and IP65 rating	L	M	D	C	M	8	5	1	C

- (1) Contact the factory for product details.  
 (2) Closed loop control delivers encoder feedback and hMT enhanced motor performance.

### Accessories

description	length feet (m)	part number
<b>Communication converter</b> USB-pluggable converter to set/program communication parameters in 32- or 64-bit.		
Mates to DB9 connector	6.0 (1.8)	MD-CC404-000
Mates to M12 5-pin female connector	6.0 (1.8)	MD-CC405-000

### IP65 cordsets

Shielded cables pre-wired with straight M12 mating connectors

Communication cordset mates to 5-pin female connector	10.0 (3.0)	MD-CS600-000
Power cordset mates to 4-pin male connector	10.0 (3.0)	MD-CS620-000
I/O cordset mates to 12-pin male connector	10.0 (3.0)	MD-CS610-000

### Replacement mating connector kit

Kits are for IP20 products. They include one 2-pin power mate, and one set (2 pieces) 7-pin multifunction mates

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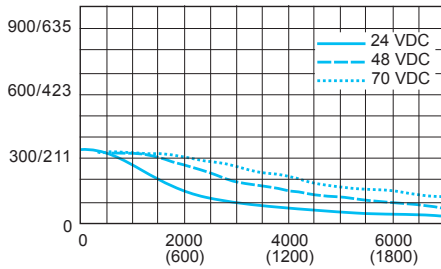
### Motor performance

LMD•85 NEMA 34 motor specifications	Motor	Stack length	Single	Double	Triple
	Holding torque Detent torque Rotor inertia Radial load limit, center of shaft Axial load limit @ 1500rpm (5000 full steps/sec) Weight (motor+driver)	oz-in N-cm oz-in N-cm oz-in-sec <sup>2</sup> kg-cm <sup>2</sup> lbs kg lbs kg lbs kg	oz-in N-cm oz-in-sec <sup>2</sup> kg-cm <sup>2</sup> lbs kg lbs kg	336 237 10.9 7.7 0.0127 0.90 65 29.4 20 9 4.45 2.02	480 339 14.16 10.0 0.0191 1.35 65 29.4 20 9 5.65 2.56

### LMD•85 NEMA 34 speed torque (1)

#### Single stack length

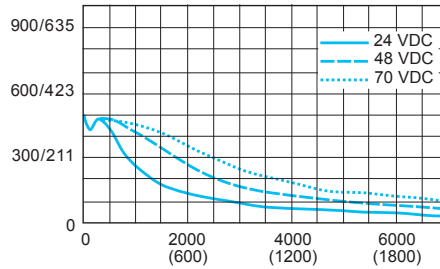
Torque in  
Oz-In / N-cm



Speed of rotation in full steps per second (rpm)

#### Double stack length

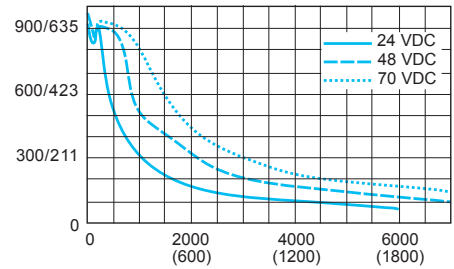
Torque in  
Oz-In / N-cm



Speed of rotation in full steps per second (rpm)

#### Triple stack length

Torque in  
Oz-In / N-cm



Speed of rotation in full steps per second (rpm)

(1) Test conditions: 100% current with damper simulating load.