

#### I MD•F42 Fthernet TCP/IP

#### Product overview

Robust Lexium MDrive® Ethernet TCP/IP products integrate 1.8° 2-phase stepper motors with control electronics including an Ethernet controller that supports user-selectable protocols: Profinet, EtherNet/IP, and ModbusTCP. An optional encoder delivers hMT closed loop performance.

hMT closed loop performance is available in products with either a multi-turn absolute encoder or incremental magnetic encoder. Closed loop performance maintains functional motor control to prevent loss of synchronization, offers variable current control, torque control, and use of the motor's full torque range without derating.

Multi-turn absolute encoders may benefit users by detecting and storing position information, even when powered down. This can eliminate homing routines and reduce setup time at system startup.

Lexium MDrive products are ODVA-compliant adapter class devices capable of explicit or implicit messaging. Compact motion control solutions that interface with many manufacturer's systems.

#### Application areas

Especially well suited for industrial applications, products include an IP65 rated version with circular M12 connectors.

Lexium MDrive products can reduce machine complexity, size and cost in many stepper and servo motor applications. Their high degree of integration can increase system reliability by reducing the number of individual components, eliminating multiple potential failure points.



LMD•E42 Lexium MDrive Ethernet TCP/IP products: integrated NEMA17 motor and controls, IP65 & IP20-rated

#### Features overview

General	NEMA17 1.8° 2-phase stepper motor integrated with robust control electronics,					
	including programmable motion controller					
	Advanced current control for exceptional performance and smoothness					
Input power	+12 to +48 VDC single supply					
Communication protocols	EtherNet/IP					
	Profinet					
	ModbusTCP					
	MCode/TCP					
Encoder options	Multi-turn absolute or incremental magnetic					
Motion	20 microstep resolutions up to 51,200 steps per rev including: Degrees, Metric, Arc Minutes					
	336 user program labels / 11,120 bytes flash memory					
	0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments					
I/O, sourcing or sinking	+5 to +24 VDC signal inputs					
	12-bit analog input (1)					
	5.5mA high-speed signal output					
Protection	084°C temperature warning, user selectable					
	IP20, IP65 ratings					
Warranty	4 year, conditional					

<sup>(1)</sup> Not available on products with multi-turn absolute encoder.



### LMD•E42 Ethernet TCP/IP

#### **Specifications**

Communication	Туре		Ethernet TCP/IP				
	Protocols		Profinet EtherNet/IP (ODVA compliant)				
			Modbus TCP				
			MCode/TCP on configuration port				
	Baud rate		100 Mbps				
	Configuration port		503				
Input power	Voltage	VDC	+12+48				
	Current maximum (1)	Amp	2.0				
Motor	Frame size	NEMA	17				
		inches	1.7				
		mm	42				
	Performance levels		standard torque				
	Holding torque	oz-in	4488				
		N-cm	31 62				
	Length	stack sizes	1, 2 & 3				
Thermal	Operating temp	Heat sink maximum	85°C				
	non-condensing	Motor maximum	100°C				
Protection	Туре	Temp warning	084°C, user selectable				
		IP rating	IP20, IP65				
		Earth grounding	via product chassis ground lug				
/O sourcing or sinking	One analog input (2)	Resolution	12 bit				
		Voltage range	0+5 VDC, 0+10 VDC, 020 mA, 420 mA				
	Three signal inputs	Voltage range	+5+24 VDC, TTL level compatible				
		Protection	over temp, short circuit, transient, over voltage, inductive clamp				
	One high-speed signal	Current open collector/emitter	5.5 mA				
	output	Voltage open collector	+60 VDC				
		Voltage open emitter	+7 VDC				
Aux. logic input	Voltage range (2)		+12+24 VDC				
Encoder options	Multi-turn absolute	Position update / retention	30 days on internal power; 5 years with optional battery pack				
	Incremental magnetic	Line count	1000 lines / 4000 edges per rev				
Motion	Microstep resolution	Number of settings	20				
		Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 arc minute/µstep), 25400 (0.001mm/µstep)				
	Counters	Туре	position, encoder/32 bit				
		Edge rate maximum	5 MHz				
	Velocity	Range	+/- 2,560,000				
		Resolution	0.5961 steps per second				
	Accel/Decel	Range	1.5 x 10 <sup>9</sup> steps persecond <sup>2</sup>				
		Resolution	90.9 steps per second <sup>2</sup>				
Software (3)	Profinet	Output slot 1	128 bytes, 38 registers				
		Input slot 2	128 bytes, 34 registers				
		Register mapping	variable, user defined				
	EtherNet/IP	Device class	adapter				
		Message types	explicit or implicit				
		Objects	identity, assembly, TCP, Ethernet link, manufacturer specific				
	Modbus TCP	Device ID	43/14d (0x2B/0x0E)				
		Function codes	public and manufacturer specific				
	MCode/TCP	Proprietary	programming over Ethernet				



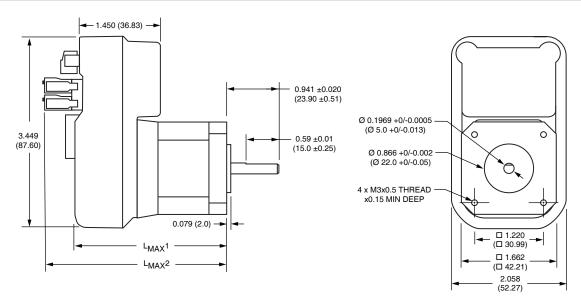
 <sup>(1)</sup> Actual power supply current will depend on voltage and load.
 (2) Not available on products with multi-turn absolute encoder.
 (3) When input voltage is removed, maintains power only to control and feedback circuits.
 (4) Closed-loop models with encoder only.

#### LMD•E42 Ethernet TCP/IP

#### **Dimensions**

#### LMD•42 NEMA17 motor, IP20-rated

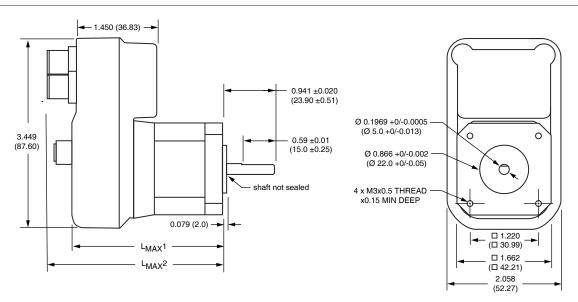
inches (mm)



Motor stack length	Lmax1	Lmax2
Single	2.48 (63.0)	3.22 (81.8)
Double	2.71 (69.0)	3.46 (88.0)
Triple	3.04 (77.3)	3.78 (96.0)

#### LMD•42•C NEMA17 motor, IP65-rated

inches (mm)



Motor stack length	Lmax1	Lmax2
Single	2.78 (70.7)	3.39 (86.0)
Double	2.98 (75.7)	3.58 (91.0)
Triple	3.33 (84.7)	3.94 (100.0)

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#### LMD•E42 Ethernet TCP/IP

#### IP20-rated products

#### LEDs

two signal indicators

#### Connectors

P1: Power 2-pin screw lock

P2: I/O & multifunction

2 keyed 7-pin spring lock

P3: Communication RJ45

Chassis ground one #6-32 screw

#### IP65-rated products

Connector P1: Power M12 4-pin male

Chassis ground one #6-32 screw

Connectors

P2: I/O & multifunction M12 12-pin male

P3: Communication M12 4-pin female

LEDs

two signal indicators





#### Part numbers

example part number	L	M	D	С	Ε	4	2	1	С
Product LMD = Lexium MDrive with standard hybrid stepper motor	L	М	D	С	Ε	4	2	1	С
Control type C = Closed loop / with hMT and incremental magnetic encoder (1) A = Closed loop / with hMT and multi-turn absolute encoder (1) O = Open loop / no hMT or encoder	L	М	D	С	Е	4	2	1	С
Communication type E = EtherNet/IP, ModbusTCP, Profinet, MCode/TCP	L	М	D	С	Ε	4	2	1	С
Flange size 42 = NEMA 17 1.7" / 42mm	L	М	D	С	Ε	4	2	1	С
Motor length 1 = single stack 2 = double stack 3 = triple stack	L	М	D	С	Е	4	2	1	С
Variation — omit from part number if unwanted C = M12 circular connectors and IP65 rating	L	М	D	С	E	4	2	1	С

<sup>(1)</sup> Closed loop control delivers encoder feedback and hMT enhanced motor performance.

#### Accessories

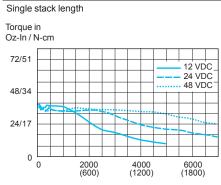
description	length feet (m)	part number
IP65 cordsets Shielded cables pre-wired with straight M12 mating connectors		
Communication cordset mates to 4-pin female connector	6.5 (2.0)	MD-CS640-000
Power cordset mates to 4-pin male connector	10.0 (3.0)	MD-CS620-000
I/O cordset mates to 12-pin male connector	10.0 (3.0)	MD-CS610-000
Back-up battery pack for Absolute Encoder models Extend stored position data up to 5-years for 1 to 6 LMDs with absolute encoder		
Battery pack, DIN-rail mount. Uses 3 AA batteries, not provided	_	ICP0531
LMD mating cable(s) with crimp connector to flying lead end	3.3 (1.0)	PD02-0531-FL1
PLC mating cable with crimp connector to flying lead end	3.3 (1.0)	PD04-0531-FL1
Replacement mating connector kit Kits are for IP20 products. They include one 2-pin power mate, and one set (2 pieces) 7-pin multifunction mates	_	CK-15

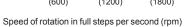
#### LMD•E42 Ethernet TCP/IP

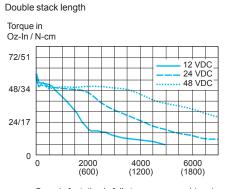
#### Motor performance

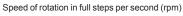
Motor	Stack length	Single	Double	Triple	
Holding torque	oz-in	44	58	88	
Holding torque	N-cm	31	41	62	
Detent torque	oz-in	1.7	2.1	3.5	
Detent torque	N-cm	1.2	1.5	2.5	
Rotor inertia	oz-in-sec²	0.0005	0.0008	0.0012	
Notor mertia	kg-cm <sup>2</sup>	0.038	0.057	0.082	
Radial load limit, center of shaft	Ibs	8.5	8.5	8.5	
Radial load littlit, certier of strait	kg	3.8	3.8	3.8	
Axial load limit @ 1500rpm	Ibs	10	10	10	
(5000 full steps/sec)	kg	4.5	4.5	4.5	
Weight (motor+driver)	oz	13.6	16.0	18.4	
weight (motor-anver)	g	385	454	522	

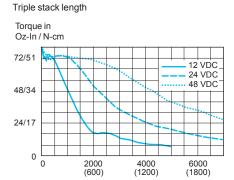
#### LMD•42 NEMA 17 speed torque (1)











Speed of rotation in full steps per second (rpm)

(1) Test conditions: 100% current with damper simulating load.